

# Directed hypergraph connectivity augmentation by hyperarc reorientation

*Joint work with: Moritz Mühlenthaler and Zoltán Szigeti*

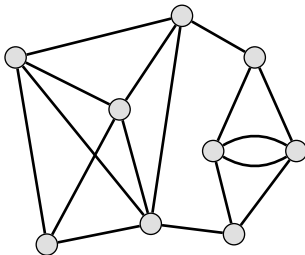
Benjamin Peyrille

November 23th 2023

# Connectivity

## Edge connectivity

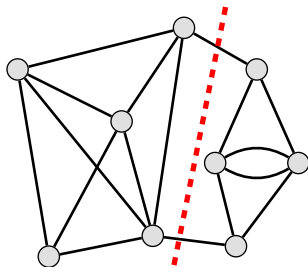
A graph  $G = (V, E)$  is  **$k$ -edge-connected** if and only if for all non-empty vertex set  $X \neq V : d(X) \geq k$ .



# Connectivity

## Edge connectivity

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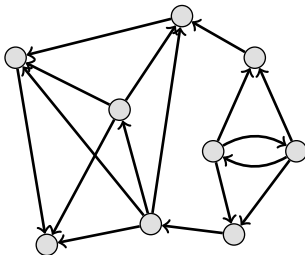


This graph is 2-edge-connected.

# Connectivity

## Arc connectivity

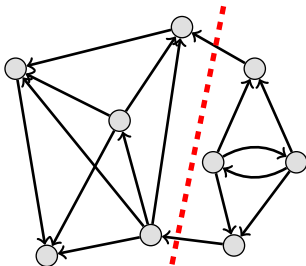
A graph orientation  $\vec{G} = (V, A)$  is  **$k$ -arc-connected** if and only if for all non-empty vertex set  $X \neq V$ :  $d^-(X) \geq k$ .



# Connectivity

## Arc connectivity

A graph orientation  $\vec{G} = (V, A)$  is  **$k$ -arc-connected** if and only if for all non-empty vertex set  $X \neq V$ :  $d^-(X) \geq k$ .



This orientation is 0-arc-connected.

## Augmentation results

### Weak Orientation Theorem (Nash-Williams, 1960)

An undirected graph admits a  $k$ -arc-connected orientation if and only if it is  $2k$ -edge-connected.

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### Arc-Connectivity Augmentation (Ito et al., 2021)

Let  $G = (V, E)$  be an undirected  $(2k + 2)$ -edge-connected graph,  $D$  be a  $k$ -arc-connected orientation of  $G$ .

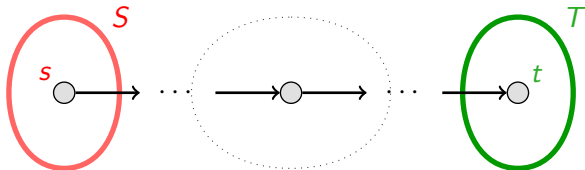
Then, there exist orientations  $D_1, D_2, \dots, D_\ell$  of  $G$  such that

- ▶  $D_i$  is obtained from  $D_{i-1}$  by reversing an arc of  $D_{i-1}$ ,
- ▶  $\ell \leq |V|^3$ ,
- ▶  $\lambda(D) \leq \lambda(D_1) \leq \lambda(D_2) \leq \dots \leq \lambda(D_\ell) = k + 1$ .

Furthermore, such orientations can be found in polynomial time.

## The key idea of Ito et al.

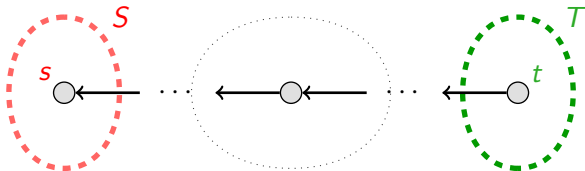
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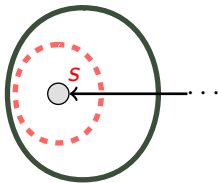
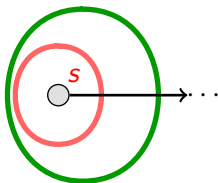


We will iteratively reverse  $(s, t)$ -paths connecting a minimal set  $S$  of in-degree  $k$  (**in-tight**  $\mathcal{T}^-$ ) to a minimal set  $T$  of out-degree  $k$  (**out-tight**  $\mathcal{T}^+$ ).

We call  $s$  a **source** and  $t$  a **sink**.

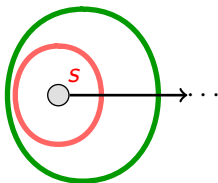
# The dangers

Connectivity loss by path-reversal.

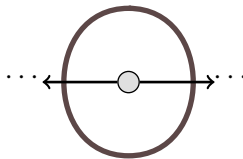
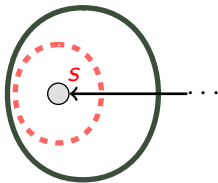
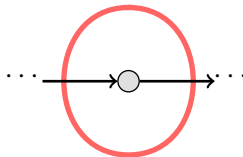


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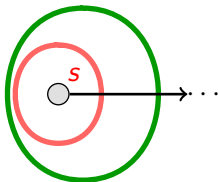


Connectivity loss by  
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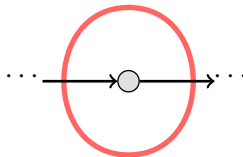


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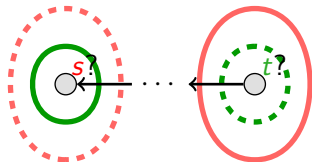
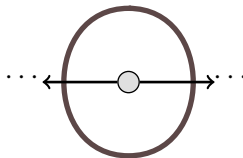
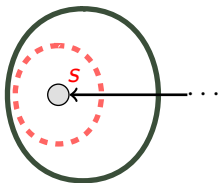
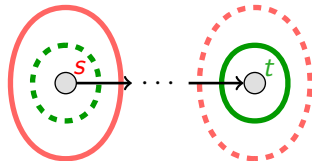
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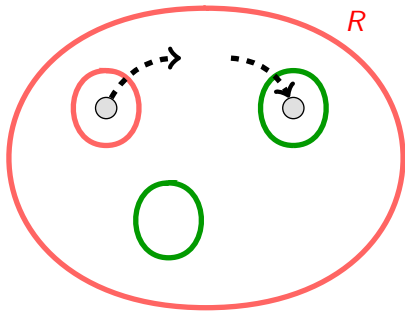


Useless paths.



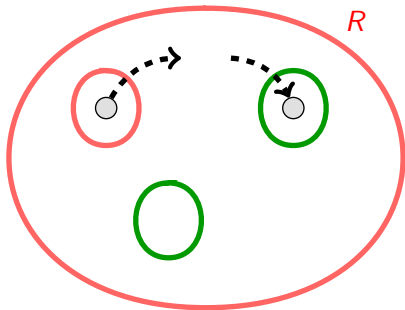
## How to preserve connectivity: path errors

We introduce a new family  $\mathcal{R}^-$  containing the minimum **in**-tight sets containing an **out**-tight set.



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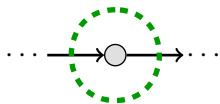


Restraining our paths to  $R$  prevents path-reversal connectivity loss. Thus, we search for  $s$  and  $t$  in  $R$ .

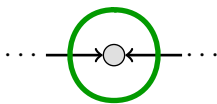
## How to preserve connectivity: arc errors

We reverse our  $(s, t)$ -path from end to start.

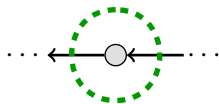
For any vertex set  $X$  entered that doesn't contain  $t$ ,  $d^+(X)$  is temporarily decreased by 1.



Step 1



Step 2

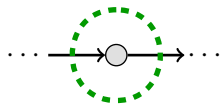


Step 3

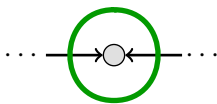
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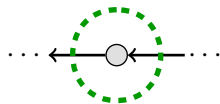
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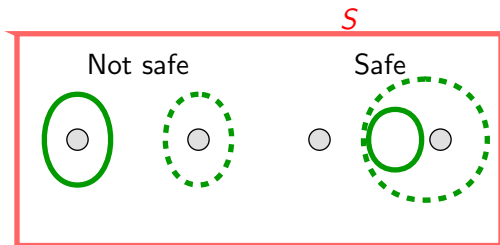
Our  $(s, t)$ -path must not enter any **out**-tight set that doesn't contain  $t$ .



## How to do something: safe sources

A vertex  $s$  is a safe source for  $S \in \mathcal{M}^-$  if:

- ▶ (Safe) If  $s \in Y \in \mathcal{T}^+$  then  $S \subset Y$ .
- ▶ (Useful) If  $s \in Z$  such that  $d^+(Z) = k + 1$  and  $S \not\subseteq Z$  then there exists an out-tight set in  $Z$  that doesn't contain  $s$ .



# Algorithm

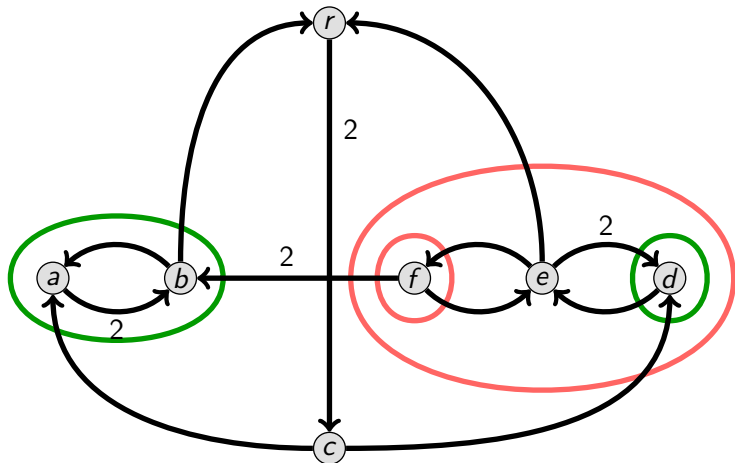
- ▶ Pick a set  $R \in \mathcal{R}^-$  (If none, flip orientation).
- ▶ Pick a safe source  $s$  in a minimal set  $S \in \mathcal{T}^-$  with  $S \subseteq R$ .
- ▶ Search for a minimum out-tight set  $T$  in  $R$ .  
If the search enters an out-tight set, don't exit it.
- ▶ Once the search gets inside a minimum out-tight set  $T$ , find a safe sink  $t$  in  $T$ .
- ▶ Reverse the search  $(s, t)$ -path!

Because of the search rule, the path never leaves any out-tight set.

Repeat until no tight sets remain  $\implies \lambda(D) = k + 1$ .

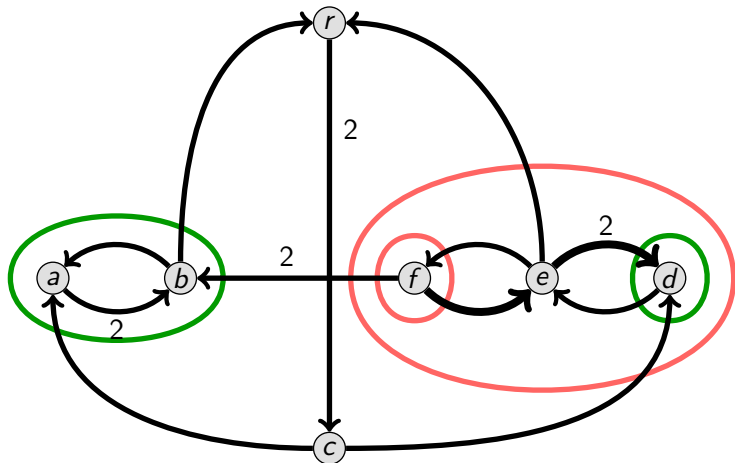
# Let's reconfigure!

Context:  $G$  is 4-edge-connected and  $\vec{G}$  is 1-arc-connected.



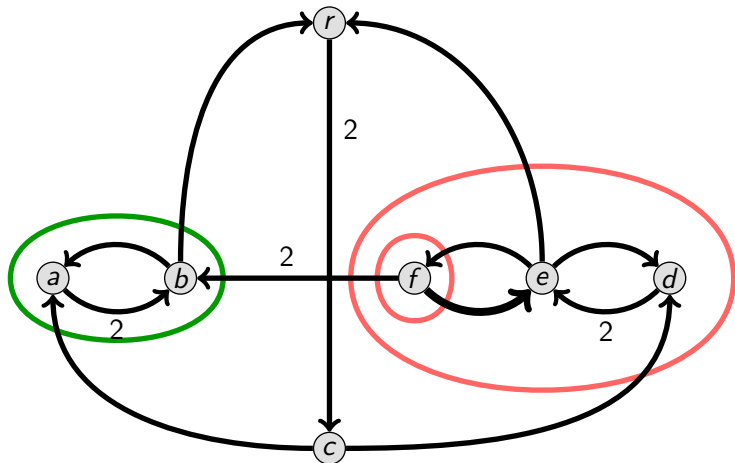
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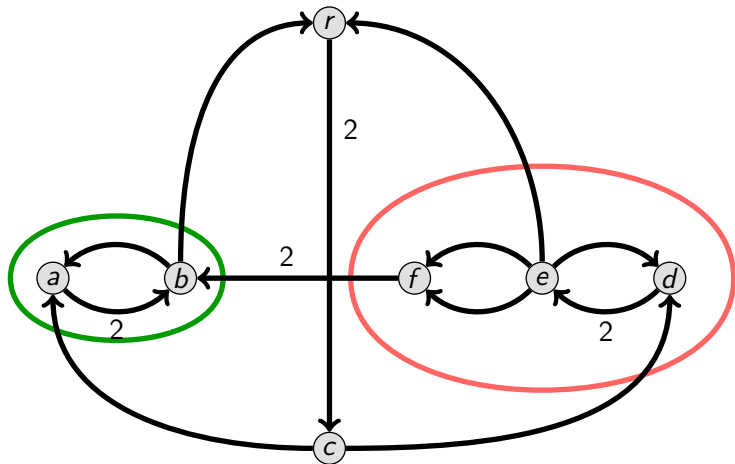
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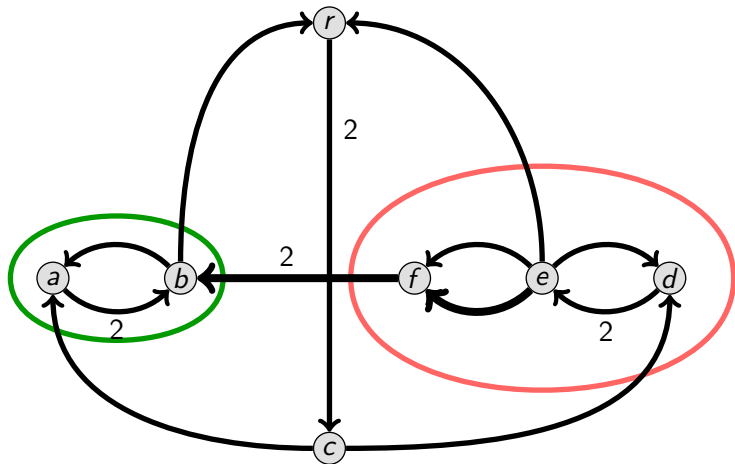
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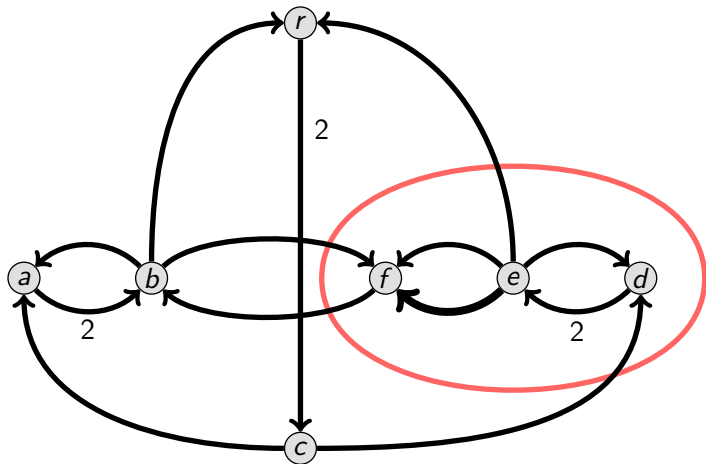
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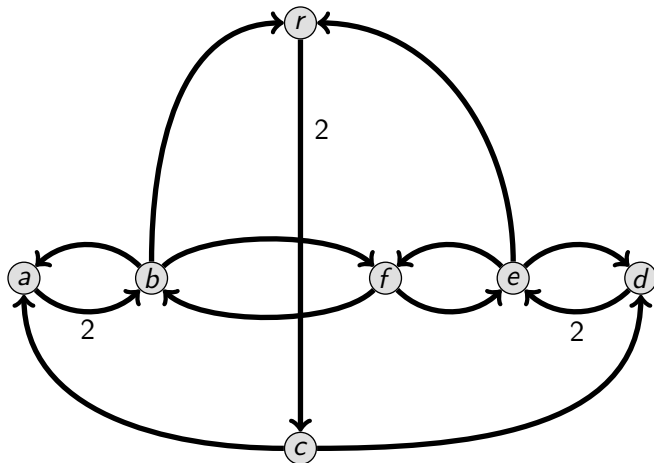
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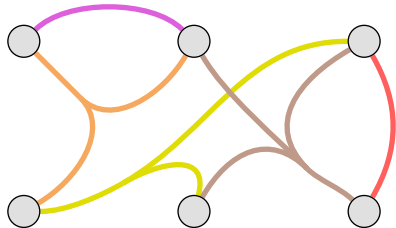


# Hypergraphs

## Hypergraph

A hypergraph  $\mathcal{H} = (V, \mathcal{E})$  is composed of:

- ▶ Vertices in  $V$
- ▶ Hyperedges in  $\mathcal{E}$ , linking vertices together

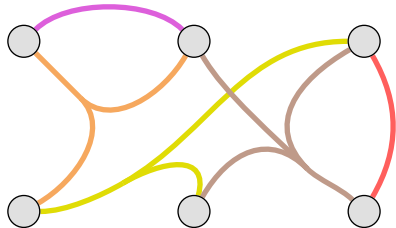


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## Partition-connectivity

$\mathcal{H}$  is  $(k, k)$ -**partition-connected** if for any partition  $\mathcal{P}$  of  $V$ , at least  $k|\mathcal{P}|$  hyperedges intersect at least 2 members of  $\mathcal{P}$ :

$$e_{\mathcal{H}}(\mathcal{P}) \geq k|\mathcal{P}|.$$

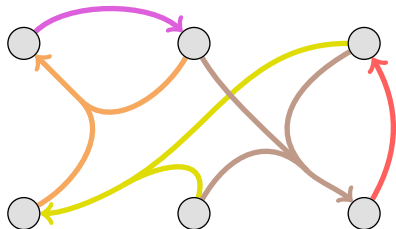
Partition-connectivity is a stronger version of edge-connectivity.

# Directed Hypergraphs

## Directed Hypergraph

A directed hypergraph  $\vec{\mathcal{H}} = (V, \mathcal{A})$  is composed of:

- ▶ Vertices in  $V$
- ▶ Hyperarcs in  $\mathcal{A}$  with a unique head vertex

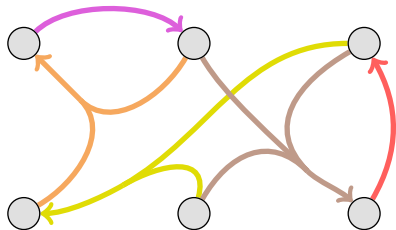


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## Hyperarc-connectivity

$\vec{\mathcal{H}}$  is  **$k$ -hyperarc-connected** if for any non-empty vertex set  $X \neq V$ , at least  $k$  hyperarcs enter  $X$ .

## Towards generalization

Theorem on hypergraph orientations (Frank, Király, Király, 2003)

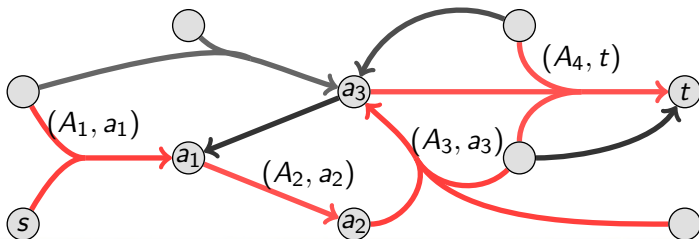
A hypergraph  $\mathcal{H}$  admits a  $k$ -hyperarc-connected orientation if and only if it is  $(k, k)$ -partition-connected.

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Most of the previous ideas work for connectivity augmentation!  
 Instead of finding good paths, we find good hyperpaths and reverse them.

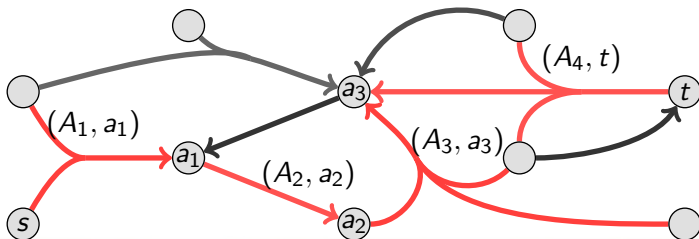


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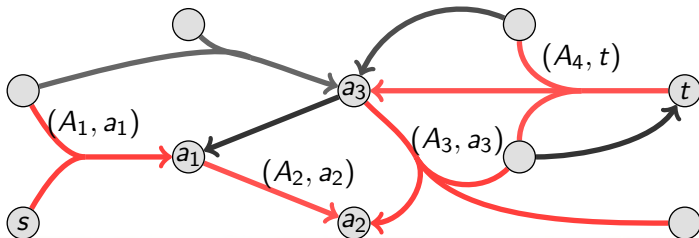


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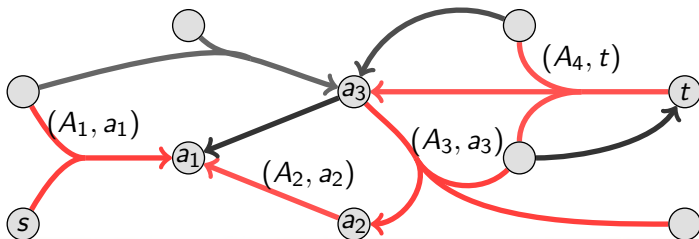


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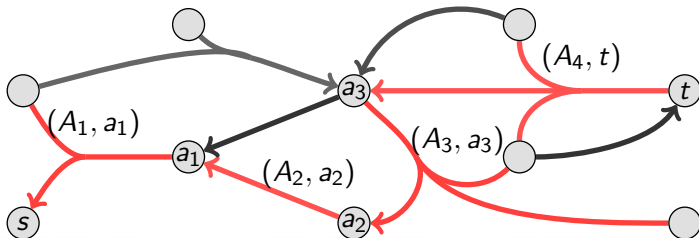


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## Hyperarc-Connectivity Augmentation

Let  $\mathcal{H} = (V, E)$  be a  $(k + 1, k + 1)$ -partition-connected hypergraph and  $\mathcal{D}$  be a  $k$ -hyperarc-connected orientation of  $\mathcal{H}$ .

Then, there exist orientations  $\mathcal{D}_1, \mathcal{D}_2, \dots, \mathcal{D}_\ell$  of  $\mathcal{H}$  such that

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Furthermore, such orientations can be found in polynomial time.

This is the first algorithm to compute a  $k$ -hyperarc-connected orientation of a hypergraph.

## Frank's result : path and cycle reversing

### Reconfiguration of two $k$ -arc-connected orientations (1982)

Given two  $k$ -arc-connected orientations  $D, D'$  of a  $2k$ -edge-connected graph  $G$ , there exist  $k$ -arc-connected orientations  $D = D_1, D_2, \dots, D_\ell = D'$  of  $G$  such that  $D_i$  is obtained from  $D_{i-1}$  by reversing a path or a cycle.

Applying this theorem arc-by-arc may decrease the connectivity by one temporarily.

## Ito et al.'s result on reconfiguration

### Reconfiguration reachability of $k$ -arc-connected orientations

Given two  $k$ -arc-connected orientations  $D, D'$  of a  $(2k + 2)$ -edge-connected graph  $G$ , there exist  $k$ -arc-connected orientations  $D = D_1, D_2, \dots, D_\ell = D'$  of  $G$  such that  $D_i$  is obtained from  $D_{i-1}$  by reversing an arc of  $D_{i-1}$ .

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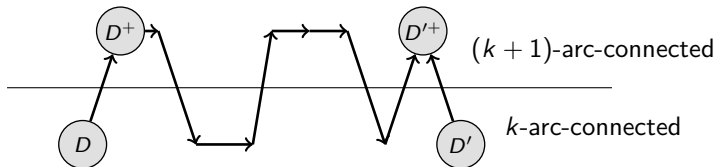
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Furthermore, such orientations can be found in polynomial time.

We augment  $D$  and  $D'$  to  $(k + 1)$ -arc-connectivity, then we apply Frank's reconfiguration algorithm arc-by-arc.





## It works on hypergraphs

We can adapt the proof of Frank to work on hypergraph orientations, leading to the following generalization.

### Reconfiguration reachability of $k$ -hyper-connected orientations

Given two  $k$ -hyperarc-connected orientations  $\mathcal{D}, \mathcal{D}'$  of a  $(k + 1, k + 1)$ -partition-connected hypergraph  $\mathcal{H}$ , there exist  $k$ -hyperarc-connected orientations  $\mathcal{D} = \mathcal{D}_1, \mathcal{D}_2, \dots, \mathcal{D}_\ell = \mathcal{D}'$  of  $\mathcal{H}$  such that  $\mathcal{D}_i$  is obtained from  $\mathcal{D}_{i-1}$  by reorienting an hyperarc of  $\mathcal{D}_{i-1}$ .

Furthermore, such orientations can be found in polynomial time.

## Conclusion

We generalized the results of Ito et al. to hypergraphs:

- ▶ We provided the first combinatorial algorithm for computing a  $k$ -hyperarc-connected orientation of a hypergraph.
- ▶ We show it is possible to reconfigure a  $k$ -hyperarc-connected orientation of a hypergraph into any other, if the hypergraph is  $(k + 1, k + 1)$ -partition-connected.

Open questions:

- ▶ Our upper bound on the number of reorientated hyperarcs is  $|V|^3$ . Can we do lower? (maybe  $|V|^2$ )
- ▶ The target when augmenting is  $d^-(X) \geq k$ . For which  $f$  can we replace  $k$  with  $f(X)$ ?

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- ▶ We show it is possible to reconfigure a  $k$ -hyperarc-connected orientation of a hypergraph into any other, if the hypergraph is  $(k + 1, k + 1)$ -partition-connected.

Open questions:

- ▶ Our upper bound on the number of reorientated hyperarcs is  $|V|^3$ . Can we do lower? (maybe  $|V|^2$ )
- ▶ The target when augmenting is  $d^-(X) \geq k$ . For which  $f$  can we replace  $k$  with  $f(X)$ ?

Merci !